

ECE241 – Digital Systems Finite State Machines (review)

Fall 2023 – Bruno Korst, P.Eng.

1



Definitions

- Synchronous Sequential Machine
 - Machine whose present outputs are a function of the present state

OR

- Machine whose present outputs are a function of the present inputs and the present state.
- Synchronous → "responds to a clock"
- Sequential logic system → combinational logic + storage

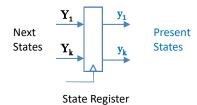
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2



Definitions

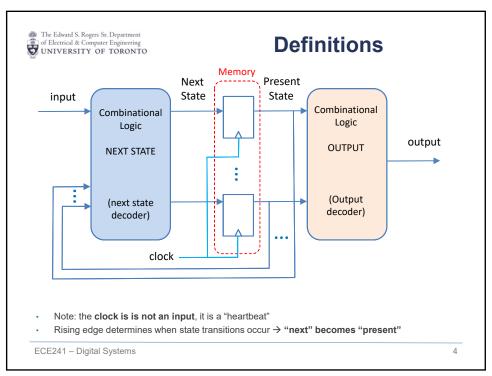
- State is "a set of values that is measured at different locations within the machine" (stored, in clocked D-FF, registers)
 - Present state: state of the system at the present
 - Next state: state to which the system will enter on the next clock edge.

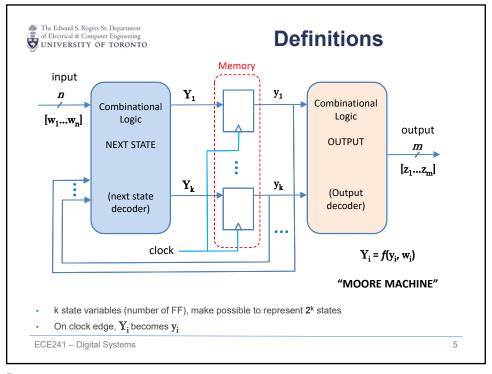


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3

3







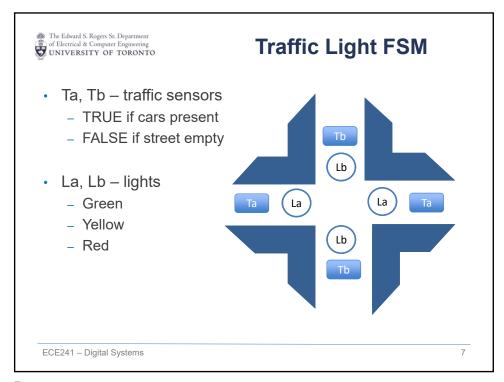
Traffic Light FSM

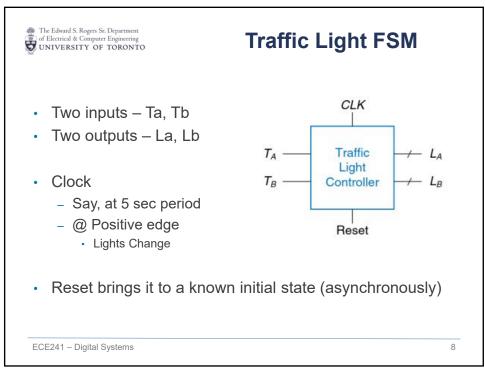
The problem

- There is an intersection of two busy roads which needs traffic lights to prevent collisions.
- These lights are to be controlled by traffic sensors, which indicate whether there are cars present or not.

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6







- A systematic approach to the design
 - 1. Draw the state transition diagram
 - 2. Create the state transition table
 - 3. Encode the states on the state transition table
 - 4. Derive the logic expressions, minimize them
 - 5. Create the output table, encode it
 - 6. Derive the logic expressions, minimize them
 - 7. Draw the circuit, implement it
 - · On "old-school" hardware, in code, on HDL

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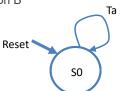
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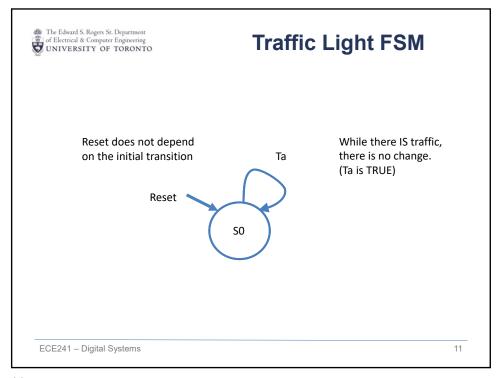
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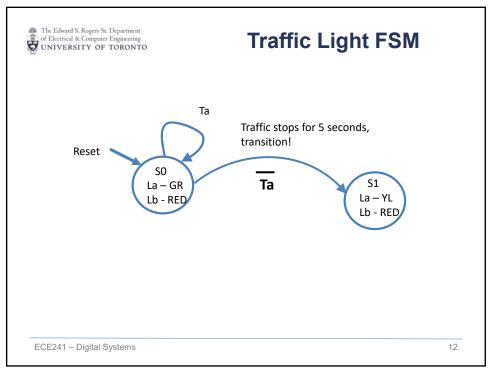
- State Transition Diagram
 - States are represented by circles, transitions by arcs
 - Reset green on "A" street, red on "B" street
 - Every 5 seconds (clock), examine sensors (Ta, Tb) and decide:
 - Is traffic present on A if so, lights do not change
 - · When no more traffic on A for 5 seconds light turns yellow on A
 - · 5 seconds later, red on A, green on B

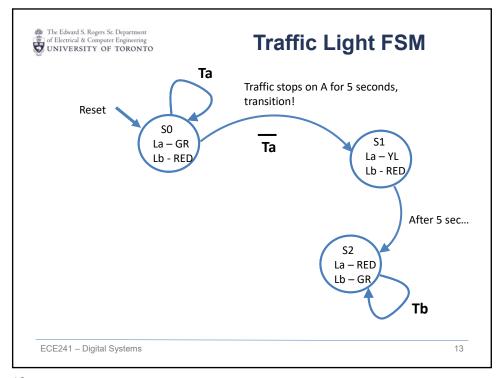


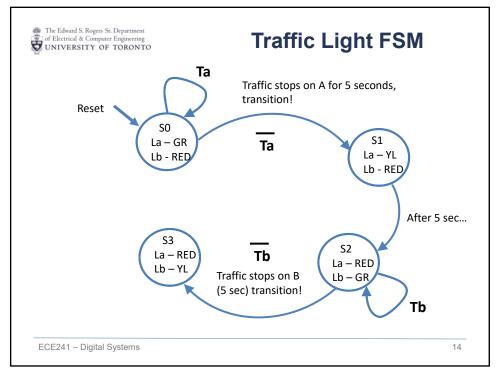
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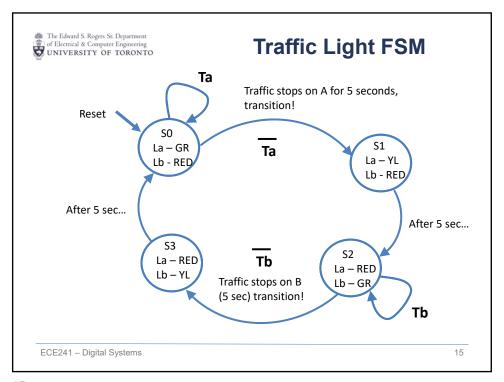
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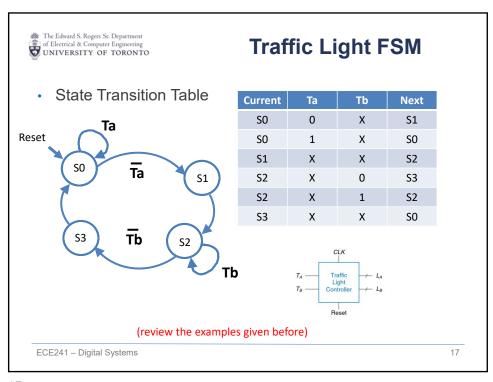


Traffic Light FSM

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16



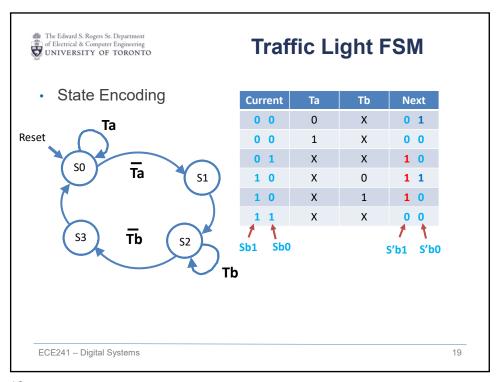


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18





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20



Logic Expressions

Current	Та	Tb	Ne	ext
0 0	0	Χ	0	1
0 0	1	Χ	0	0
0 1	X	Χ	1	0
1 0	Χ	0	1	1
1 0	X	1	1	0
1 1	X	X	0	0
Sb1 Sb0)	9	/ 5'b1	S'b0

$$\begin{aligned} \mathbf{S'b_1} &= \overline{Sb_1}Sb_0 + Sb_1\overline{Sb_0}\,\overline{T_b} + Sb_1\overline{Sb_0}T_b \\ \mathbf{S'b_0} &= \overline{Sb_1}\,\overline{Sb_0}\,\overline{T_a} + Sb_1\overline{Sb_0}\,\overline{T_b} \end{aligned}$$

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21

21



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Logic Expressions

Current	Та	Tb	Next
0 0	0	Χ	0 1
0 0	1	Χ	0 0
0 1	Х	Х	1 0
1 0	Х	0	1 1
1 0	Χ	1	10
1 1	Χ	Χ	0 0
Sb1 Sb0)	:	/

$$S'b_{1} = \overline{Sb_{1}}Sb_{0} + Sb_{1}\overline{Sb_{0}}\overline{T_{b}} + Sb_{1}\overline{Sb_{0}}\overline{T_{b}}$$
$$S'b_{0} = \overline{Sb_{1}}\overline{Sb_{0}}\overline{T_{a}} + Sb_{1}\overline{Sb_{0}}\overline{T_{b}}$$

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22



• State Transition Table – next states from current states

Current	Та	Tb	Next	
0 0	0	X	0 1	
0 0	1	Χ	0 0	
0 1	Х	X	1 0	
1 0	Х	0	1 1	
1 0	Х	1	1 0	
1 1	Х	Х	0 0	
1 1			1 1	
Sb1 Sb0		9	5'b1	0 0

$$S'b_1 = \overline{Sb_1}Sb_0 + Sb_1\overline{Sb_0}$$

$$S'b_0 = \overline{Sb_1}\overline{Sb_0}\overline{T_a} + Sb_1\overline{Sb_0}\overline{T_b}$$



$$\mathbf{S'b_1} = \mathbf{Sb_1} \oplus \mathbf{Sb_0}$$

$$S'b_0 = \overline{Sb_1} \, \overline{Sb_0} \, \overline{T_a} + Sb_1 \overline{Sb_0} \, \overline{T_b}$$

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23

23

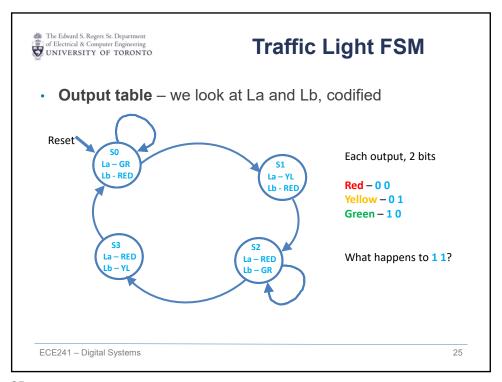


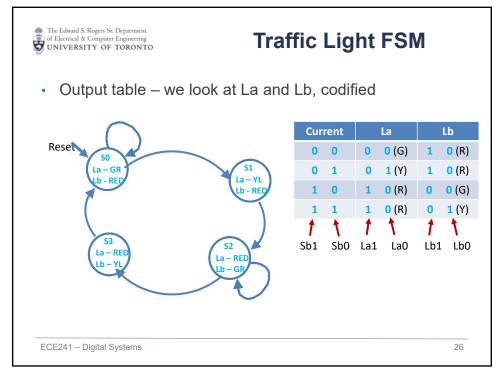
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24







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27

27



Traffic Light FSM

· Output table – we look at La and Lb, codified

Curi	rent		La		Lb
0	0	0	0 (G)	1	0 (R)
0	1	0	1 (Y)	1	0 (R)
1	0	1	0 (R)	0	0 (G)
1	1	1	0 (R)	0	1 (Y)
<i>†</i>	1	t	1	†	1
Sb1	Sb0	La1	La0	Lb1	Lb0

$$La_{1} = Sb_{1}$$

$$La_{0} = \overline{Sb_{1}}Sb_{0}$$

$$Lb_{1} = \overline{Sb_{1}}$$

$$Lb_{0} = S_{1}S_{0}$$

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28



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29

29



Traffic Light FSM

· We've got equations for next states from current states

A 2 bit state register...

$$S'b_1 = Sb_1 \oplus Sb_0$$

$$S'b_0 = \overline{Sb_1} \overline{Sb_0} \overline{T_a} + Sb_1 \overline{Sb_0} \overline{T_b}$$

$$T_A = Sb_1 \otimes Sb_0 \otimes S$$

But that does not say anything about the output...

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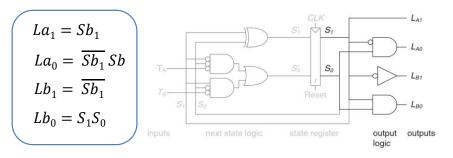
30

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So



· We've ALSO got equations for outputs, which result in...



Note: Outputs depend only on the present state → MOORE MACHINE

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31

31



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32

