

Difference Equations and Implementation 2.4 Difference Equations

Finite vs. Infinite Impulse Response

For causal LTI systems, h(n) = 0 for n < 0.

Finite impulse response (FIR):

$$y(n) = \sum_{k=0}^{M-1} h(k) x(n-k)$$

Infinite impulse response (IIR):

$$y(n) = \sum_{k=0}^{\infty} h(k) x(n-k)$$

How would one realize these systems?

Difference Equations and Implementation

Reference:

Section 2.4 and 2.5 of

John G. Proakis and Dimitris G. Manolakis, *Digital Signal Processing: Principles, Algorithms, and Applications*, 4th edition, 2007.

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Difference Equations and Implementation
 2.4 Difference Equations

 Finite vs. Infinite Impulse Response

 Implementation:
 Two classes

 Finite impulse response (FIR):

$$y(n) = \sum_{k=0}^{M-1} h(k)x(n-k)$$
 ononrecursive systems

 Infinite impulse response (IIR):
 $y(n) = \sum_{k=0}^{\infty} h(k)x(n-k)$
 recursive systems

 $y(n) = \sum_{k=0}^{\infty} h(k)x(n-k)$
 $y(n) = \sum_{k=0}^{\infty} h(k)x(n-k)$
 $x(n-k)$
 $y(n) = \sum_{k=0}^{\infty} h(k)x(n-k)$

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System Realization

There is a practical and computationally efficient means of implementing all FIR and a family of IIR systems that makes use of



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Difference Equations and Implementation 2.4 Difference Equations

System Realization

General expression for Nth-order LCCDE:

$$\sum_{k=0}^{N} a_k y(n-k) = \sum_{k=0}^{M} b_k x(n-k) \qquad a_0 \triangleq 1$$

Initial conditions: $y(-1), y(-2), y(-3), \ldots, y(-N)$.

Need: (1) constant scale, (2) addition, (3) delay elements.

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Difference Equations and Implementation 2.5 Implementation of Discrete-time Systems

FIR System Realization: Example

Consider a 5-point local averager:

$$y(n) = \frac{1}{5} \sum_{k=n-4}^{n} x(k) \quad n = 0, 1, 2, \dots$$

• The impulse response is given by:

$$h(n) = \frac{1}{5} \sum_{k=n-4}^{n} \delta(k)$$

= $\frac{1}{5} \delta(n-4) + \frac{1}{5} \delta(n-3) + \frac{1}{5} \delta(n-2) + \frac{1}{5} \delta(n-1) + \frac{1}{5} \delta(n)$



Difference Equations and Implementation 2.5 Implementation of Discrete-time Systems

FIR System Realization: Example

Consider a 5-point local averager:

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2.5 Implementation of Discrete-time Systems Difference Equations and Implementation

FIR System Realization: Example

Consider a 5-point local averager:

$$y(n) = \frac{1}{5} \sum_{k=n-4}^{n} x(k) \quad n = 0, 1, 2, \dots$$

Memory requirements stay constant; only need to store 5 values (4 last + present).

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fixed number of adders required

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FIR System Realization: Example $y(n) = \frac{1}{5} \sum_{k=n}^{n} x(k) = \sum_{k=n}^{n} \frac{1}{5} x(k)$ $\therefore y(n) = \frac{1}{5}x(n-4) + \frac{1}{5}x(n-3) + \frac{1}{5}x(n-2) + \cdots$ $\cdots \frac{1}{5}x(n-1) + \frac{1}{5}x(n)$ x(n-4)x(n-1)x(n-2)x(n-3)x(n)1/51/5 1/5 1/5 Professor Deepa Kundur (University of TorontoDifference Equations and Implementation 14 / 23

2.5 Implementation of Discrete-time Systems

Difference Equations and Implementation



Difference Equations and Implementation 2.5 Implementation of Discrete-time Systems

IIR System Realization: Example

Consider an accumulator:

$$y(n) = \sum_{k=0}^{n} x(k)$$
 $n = 0, 1, 2, ...$ for $y(-1) = 0$.

• The impulse response is given by:





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IIR System Realization: Example

• Consider an accumulator:

$$y(n) = \sum_{k=0}^{n} x(k)$$
 $n = 0, 1, 2, ...$ for $y(-1) = 0$.

▶ IIR memory requirements seem to grow with increasing *n*!

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Difference Equations and Implementation 2.5 Implementation of Discrete-time Systems

Direct Form I vs. Direct Form II Realizations

$$y(n) = -\sum_{k=1}^{N} a_k y(n-k) + \sum_{k=0}^{M} b_k x(n-k)$$

is equivalent to the cascade of the following systems:

$$\underbrace{v(n)}_{\text{output 1}} = \sum_{k=0}^{M} b_k \underbrace{x(n-k)}_{\text{input 1}} \qquad \text{nonrecursive}$$

$$\underbrace{y(n)}_{\text{output 2}} = -\sum_{k=1}^{N} a_k y(n-k) + \underbrace{v(n)}_{\text{input 2}} \qquad \text{recursive}$$







Requires:M + N + 1 multiplications,M + N additions,M + N memory locationsProfessor Deepa Kundur (University of Toronto)Difference Equations and Implementation22 / 23

