#### Introduction to Discrete-Time Systems

Dr. Deepa Kundur

University of Toronto

Dr. Deepa Kundur (University of Toronto)

Introduction to Discrete-Time Systems

3 / 34

Chapter 1: Introduction 1.1 Signals, Systems and Signal Processing

## What is a Signal? What is a System?

- ► Signal:
  - ▶ any physical quantity that varies with time, space, or any other independent variable or variables
  - Examples: pressure as a function of altitude, sound as a function of time, color as a function of space, ...
  - $x(t) = \cos(2\pi t), x(t) = 4\sqrt{t} + t^3, x(m, n) = (m+n)^2$
- System:
  - ▶ a physical device that performs an operation on a signal
  - ▶ Examples: analog amplifier, noise canceler, communication channel, transistor, ...
  - $y(t) = -4x(t), \frac{dy(t)}{dt} + 3y(t) = -\frac{dx(t)}{dt} + 6x(t),$  $y(n) \frac{1}{2}y(n-2) = 3x(n) + x(n-2)$

## Discrete-Time Signals and Systems

#### Reference:

Sections 1.1 - 1.4 of

John G. Proakis and Dimitris G. Manolakis, Digital Signal Processing: Principles, Algorithms, and Applications, 4th edition, 2007.

Dr. Deepa Kundur (University of Toronto)

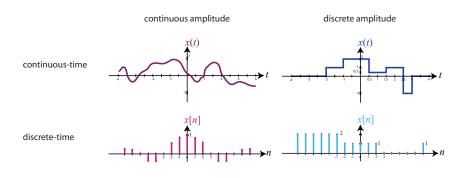
Introduction to Discrete-Time Systems

1.2 Classification of Signals

Chapter 1: Introduction

# Analog and Digital Signals

- ▶ analog signal = continuous-time + continuous amplitude
- ▶ digital signal = discrete-time + discrete amplitude



Dr. Deepa Kundur (University of Toronto) Introduction to Discrete-Time Systems

4 / 34

#### Chapter 1: Introduction 1.2 Classification of Signals

### Analog and Digital Signals

- ▶ Analog signals are fundamentally significant because we must interface with the real world which is analog by nature.
- ▶ Digital signals are important because they facilitate the use of digital signal processing (DSP) systems, which have practical and performance advantages for several applications.

Dr. Deepa Kundur (University of Toronto) Introduction to Discrete-Time Systems

5 / 34

Chapter 1: Introduction 1.2 Classification of Signals

### Deterministic vs. Random Signals

- ► Deterministic signal:
  - ▶ any signal that can be uniquely described by an explicit mathematical expression, a table of data, or a well-defined rule
  - past, present and future values of the signal are known precisely without any uncertainty
- ► Random signal:
  - ▶ any signal that lacks a unique and explicit mathematical expression and thus evolves in time in an unpredictable manner
  - ▶ it may not be possible to accurately describe the signal
  - ▶ the deterministic model of the signal may be too complicated to be of use.

### Analog and Digital Systems

▶ analog system =

analog signal input + analog signal output

- ▶ advantages: easy to interface to real world, do not need A/D or D/A converters, speed not dependent on clock rate
- ► digital system =

digital signal input + digital signal output

▶ advantages: re-configurability using software, greater control over accuracy/resolution, predictable and reproducible behavior

Dr. Deepa Kundur (University of Toronto)

Introduction to Discrete-Time Systems

Chapter 1: Introduction 1.3 The Concept of Frequency

# What is a "pure frequency" signal?

$$x_a(t) = A\cos(\Omega t + \theta) = A\cos(2\pi F t + \theta), \quad t \in \mathbb{R}$$

- ▶ analog signal,  $:: -A \le x_a(t) \le A$  and  $-\infty < t < \infty$
- $\rightarrow$  A = amplitude
- $ightharpoonup \Omega = frequency in rad/s$
- $F = \text{frequency in Hz (or cycles/s)}; \text{ note: } \Omega = 2\pi F$
- $\bullet$   $\theta$  = phase in rad

#### Continuous-time Sinusoids

$$x_a(t) = A\cos(\Omega t + \theta) = A\cos(2\pi F t + \theta), \quad t \in \mathbb{R}$$

- 1. For  $F \in \mathbb{R}$ ,  $x_a(t)$  is periodic
  - i.e., there exists  $T_p \in \mathbb{R}^+$  such that  $x_a(t) = x_a(t + T_p)$
- 2. distinct frequencies result in distinct sinusoids
  - i.e., for  $F_1 \neq F_2$ ,  $A\cos(2\pi F_1 t + \theta) \neq A\cos(2\pi F_2 t + \theta)$
- 3. increasing frequency results in an increase in the rate of oscillation of the sinusoid
  - i.e., for  $|F_1| < |F_2|$ ,  $A\cos(2\pi F_1 t + \theta)$  has a lower rate of oscillation than  $A\cos(2\pi F_2 t + \theta)$

Dr. Deepa Kundur (University of Toronto) Introduction to Discrete-Time Systems

9 / 34

11 / 34

Chapter 1: Introduction 1.3 The Concept of Frequency

#### Discrete-time Sinusoids

$$x(n) = A\cos(\omega n + \theta) = A\cos(2\pi f n + \theta), \quad n \in \mathbb{Z}$$

- 1. x(n) is periodic only if its frequency f is a rational number
  - ▶ Note: rational number is of the form  $\frac{k_1}{k_2}$  for  $k_1, k_2 \in \mathbb{Z}$
  - periodic discrete-time sinusoids:

$$x(n) = 2\cos(\frac{4}{7}\pi n), x(n) = \sin(-\frac{\pi}{5}n + \sqrt{3})$$

aperiodic discrete-time sinusoids:

$$x(n) = 2\cos(\frac{4}{7}n), x(n) = \sin(\sqrt{2\pi}n + \sqrt{3})$$

#### Discrete-time Sinusoids

$$x(n) = A\cos(\omega n + \theta) = A\cos(2\pi f n + \theta), \quad n \in \mathbb{Z}$$

- ▶ discrete-time signal (not digital),  $:: -A \le x_a(t) \le A$  and  $n \in \mathbb{Z}$
- $\rightarrow$  A = amplitude
- $\triangleright \omega = \text{frequency in rad/sample}$
- f = frequency in cycles/sample; note:  $\omega = 2\pi f$
- $\bullet$   $\theta$  = phase in rad

Dr. Deepa Kundur (University of Toronto)

Introduction to Discrete-Time Systems

10 / 34

Chapter 1: Introduction 1.3 The Concept of Frequency

#### Discrete-time Sinusoids

$$x(n) = A\cos(\omega n + \theta) = A\cos(2\pi f n + \theta), \quad n \in \mathbb{Z}$$

- 2. radian frequencies separated by an integer multiple of  $2\pi$  are identical
  - ▶ or cyclic frequencies separated by an integer multiple are identical
- 3. lowest rate of oscillation is achieved for  $\omega = 2k\pi$  and highest rate of oscillation is achieved for  $\omega = (2k+1)\pi$ , for  $k \in \mathbb{Z}$ 
  - ightharpoonup subsequently, this corresponds to lowest rate for f = k (integer) and highest rate for  $f = \frac{2k+1}{2}$  (half integer), for  $k \in \mathbb{Z}$ ; see → Figure 1.3.4 of text

### Complex Exponentials

$$e^{j\phi}=\cos(\phi)+j\sin(\phi)$$
 Euler's relation  $\cos(\phi)=rac{e^{j\phi}+e^{-j\phi}}{2}$   $\sin(\phi)=rac{e^{j\phi}-e^{-j\phi}}{2j}$  where  $j riangleq\sqrt{-1}$ 

Dr. Deepa Kundur (University of Toronto) Introduction to Discrete-Time Systems

13 / 34

15 / 34

#### Periodicity: Continuous-time

$$x(t) = x(t+T), T \in \mathbb{R}^+$$

$$A e^{j(2\pi F t + \theta)} = A e^{j(2\pi F (t+T) + \theta)}$$

$$e^{j2\pi F t} \cdot e^{j\theta} = e^{j2\pi F t} \cdot e^{j2\pi F T} \cdot e^{j\theta}$$

$$1 = e^{j2\pi F T}$$

$$e^{j2\pi k} = 1 = e^{j2\pi F T}, k \in \mathbb{Z}$$

$$T = \frac{k}{F} k \in \mathbb{Z}$$

$$T_0 = \frac{1}{|F|}, k = \operatorname{sgn}(F)$$

#### Complex Exponentials

Continuous-time:  $A e^{j(\Omega t + \theta)} = A e^{j(2\pi Ft + \theta)}$ 

Discrete-time:  $A e^{j(\omega n + \theta)} = A e^{j(2\pi f n + \theta)}$ 

Dr. Deepa Kundur (University of Toronto) Introduction to Discrete-Time Systems

14 / 34

Chapter 1: Introduction 1.3 The Concept of Frequency

#### Periodicity: Discrete-time

$$x(n) = x(n+N), N \in \mathbb{Z}^+$$

$$A e^{j(2\pi f n + \theta)} = A e^{j(2\pi f (n+N) + \theta)}$$

$$e^{j2\pi f n} \cdot e^{j\theta} = e^{j2\pi f n} \cdot e^{j2\pi f N} \cdot e^{j\theta}$$

$$1 = e^{j2\pi f N}$$

$$e^{j2\pi k} = 1 = e^{j2\pi f N}, k \in \mathbb{Z}$$

$$f = \frac{k}{N} k \in \mathbb{Z}$$

$$N_0 = \frac{k'}{f}, \min |k'| \in \mathbb{Z} \text{ such that } \frac{k'}{f} \in \mathbb{Z}^+$$

Dr. Deepa Kundur (University of Toronto) Introduction to Discrete-Time Systems

#### Uniqueness: Continuous-time

For  $F_1 \neq F_2$ ,  $A\cos(2\pi F_1 t + \theta) \neq A\cos(2\pi F_2 t + \theta)$ except at discrete points in time.

Dr. Deepa Kundur (University of Toronto) Introduction to Discrete-Time Systems

17 / 34

Chapter 1: Introduction 1.3 The Concept of Frequency

#### Uniqueness: Discrete-time

- ▶ Therefore, dst-time sinusoids are unique for  $f \in [0, 1)$ .
- ▶ For any sinusoid with  $f_1 \notin [0,1)$ ,  $\exists f_0 \in [0,1)$  such that

$$x_1(n) = A e^{j(2\pi f_1 n + \theta)} = A e^{j(2\pi f_0 n + \theta)} = x_0(n).$$

- **Example:** A dst-time sinusoid with frequency  $f_1 = 4.56$  is the same as a dst-time sinusoid with frequency  $f_0 = 4.56 - 4 = 0.56$ .
- **Example:** A dst-time sinusoid with frequency  $f_1 = -\frac{7}{8}$  is the same as a dst-time sinusoid with frequency  $f_0 = -\frac{7}{8} + 1 = \frac{1}{8}$ . ▶ Figure 1.4.5 of text

#### Uniqueness: Discrete-time

Let  $f_1 = f_0 + k$  where  $k \in \mathbb{Z}$ ,

$$x_{1}(n) = A e^{j(2\pi f_{1}n+\theta)}$$

$$= A e^{j(2\pi (f_{0}+k)n+\theta)}$$

$$= A e^{j(2\pi f_{0}n+\theta)} \cdot e^{j(2\pi kn)}$$

$$= x_{0}(n) \cdot 1 = x_{0}(n)$$

Dr. Deepa Kundur (University of Toronto)

Introduction to Discrete-Time Systems

18 / 34

Chapter 1: Introduction 1.3 The Concept of Frequency

### Harmonically Related Complex Exponentials

Harmonically related 
$$s_k(t) = e^{jk\Omega_0 t} = e^{j2\pi kF_0 t}$$
, (cts-time)  $k = 0, \pm 1, \pm 2, \dots$ 

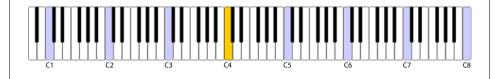
Scientific Designation	Frequency (Hz)	$k \text{ for } F_0 = 8.176$
C-1	8.176	1
C0	16.352	2
C1	32.703	4
C2	65.406	8
C3	130.813	16
C4	261.626	32
:	:	
C9	8372.018	1024

Dr. Deepa Kundur (University of Toronto) Introduction to Discrete-Time Systems

#### Chapter 1: Introduction 1.3 The Concept of Frequency

#### Harmonically Related Complex Exponentials

Scientific Designation	Frequency (Hz)	$k \text{ for } F_0 = 8.176$
C1	32.703	4
C2	65.406	8
C3	130.813	16
C4 (middle C)	261.626	32
C5	523.251	64
C6	1046.502	128
C7	2093.005	256
C8	4186.009	512



Dr. Deepa Kundur (University of Toronto) Introduction to Discrete-Time Systems

21 / 34

Chapter 1: Introduction 1.3 The Concept of Frequency

### Harmonically Related Complex Exponentials

#### Discrete-time Case:

For periodicity, select  $f_0 = \frac{1}{N}$  where  $N \in \mathbb{Z}$ :

Harmonically related 
$$s_k(n) = e^{j2\pi k f_0 n} = e^{j2\pi k n/N}$$
, (dts-time)  $k = 0, \pm 1, \pm 2, \dots$ 

▶ There are only *N* distinct dst-time harmonics:  $s_k(n), k = 0, 1, 2, \dots, N-1.$ 

## Harmonically Related Complex Exponentials

What does the family of harmonically related sinusoids  $s_k(t)$  have in common?

Harmonically related 
$$s_k(t) = e^{jk\Omega_0 t} = e^{j2\pi(kF_0)t}$$
, (cts-time)  $k = 0, \pm 1, \pm 2, \dots$ 

fund. period: 
$$T_{0,k} = \frac{1}{\text{cyclic frequency}} = \frac{1}{kF_0}$$

period:  $T_k = \text{any integer multiple of } T_0$ 

common period:  $T = k \cdot T_{0,k} = \frac{1}{F_0}$ 

Dr. Deepa Kundur (University of Toronto) Introduction to Discrete-Time Systems

Chapter 1: Introduction 1.3 The Concept of Frequency

## Harmonically Related Complex Exponentials

$$s_{k+N}(n) = e^{j2\pi(k+N)n/N}$$

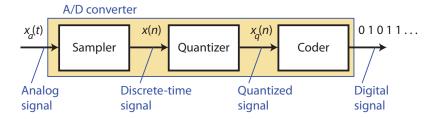
$$= e^{j2\pi kn/N} \cdot e^{j2\pi Nn/N}$$

$$= e^{j2\pi kn/N} \cdot 1$$

$$= e^{j2\pi kn/N} = s_k(n)$$

Therefore, there are only N distinct dst-time harmonics:  $s_k(n), k = 0, 1, 2, ..., N-1.$ 

# Analog-to-Digital Conversion



Dr. Deepa Kundur (University of Toronto)

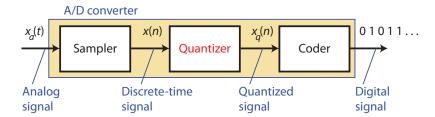
Introduction to Discrete-Time Systems

25 / 34

27 / 34

1.4 Analog-to-Digital and Digital-to-Analog Conversion

### Analog-to-Digital Conversion

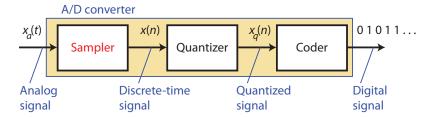


#### Quantization:

- conversion from dst-time cts-valued signal to a dst-time dst-valued signal
- quantization error:  $e_q(n) = x_q(n) x(n)$  for all  $n \in \mathbb{Z}$

Chapter 1: Introduction 1.4 Analog-to-Digital and Digital-to-Analog Conversion

### Analog-to-Digital Conversion



#### Sampling:

- ▶ conversion from cts-time to dst-time by taking "samples" at discrete time instants
- ▶ E.g., uniform sampling:  $x(n) = x_a(nT)$  where T is the sampling period and  $n \in \mathbb{Z}$

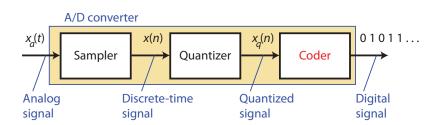
Dr. Deepa Kundur (University of Toronto)

Introduction to Discrete-Time Systems

1.4 Analog-to-Digital and Digital-to-Analog Conversion

26 / 34

Analog-to-Digital Conversion



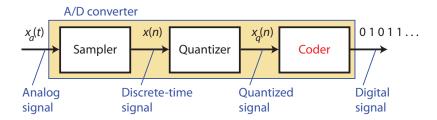
#### Coding:

- representation of each dst-value  $x_a(n)$  by a b-bit binary sequence
- e.g., if for any  $n, x_a(n) \in \{0, 1, \dots, 6, 7\}$ , then the coder may use the following mapping to code the quantized amplitude:

Dr. Deepa Kundur (University of Toronto) Introduction to Discrete-Time Systems

28 / 34

# Analog-to-Digital Conversion



#### Example coder:

000	4	100
001	5	101
010	6	110
011	7	111
	001 010	001 5 010 6

Dr. Deepa Kundur (University of Toronto) Introduction to Discrete-Time Systems

31 / 34

1.4 Analog-to-Digital and Digital-to-Analog Conversion

#### Sampling Theorem

Sampling Period = 
$$T = \frac{1}{F_s} = \frac{1}{\text{Sampling Frequency}}$$

Therefore, given the interpolation relation,  $x_a(t)$  can be written as

$$x_a(t) = \sum_{n=-\infty}^{\infty} x_a(nT)g(t-nT)$$

$$x_a(t) = \sum_{n=-\infty}^{\infty} x(n) g(t - nT)$$

where  $x_a(nT) = x(n)$ ; called bandlimited interpolation. See Figure 1.4.6 of text

#### Sampling Theorem

If the highest frequency contained in an analog signal  $x_a(t)$  is  $F_{max} = B$  and the signal is sampled at a rate

$$F_s > 2F_{max} = 2B$$

then  $x_a(t)$  can be exactly recovered from its sample values using the interpolation function

$$g(t) = \frac{\sin(2\pi Bt)}{2\pi Bt}$$

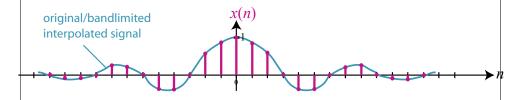
Note:  $F_N = 2B = 2F_{max}$  is called the Nyquist rate.

Dr. Deepa Kundur (University of Toronto) Introduction to Discrete-Time Systems

1.4 Analog-to-Digital and Digital-to-Analog Conversion

30 / 34

# Digital-to-Analog Conversion



- ► Common interpolation approaches: bandlimited interpolation, zero-order hold, linear interpolation, higher-order interpolation techniques, e.g., using splines
- ▶ In practice, "cheap" interpolation along with a smoothing filter is employed.

