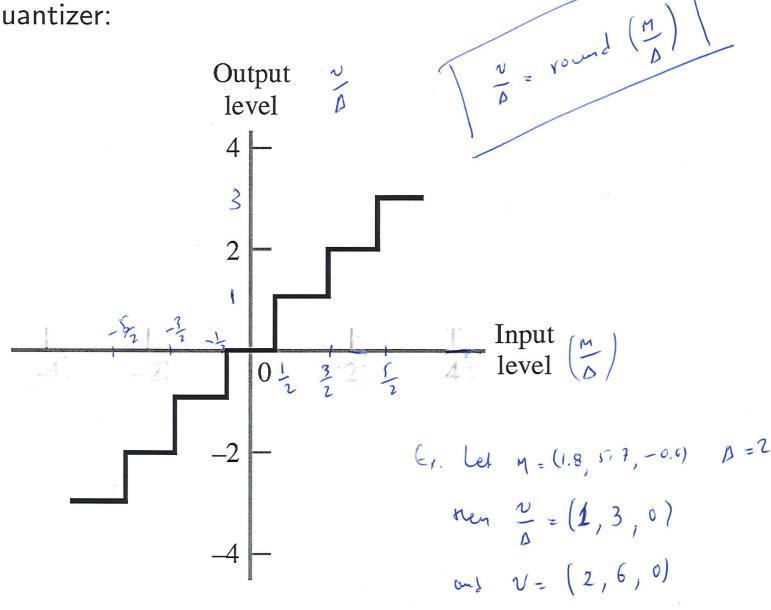
ECE462 – Lecture 4

Uniform Quantization

Midtread Quantizer:



Ex. 1: x = [1.8, 5.7, -0.6], apply midtread uniform quantizer with step size (Δ) 2

$$x_q = \left\lfloor \frac{x}{\Delta} + 0.5 \right\rfloor = \text{round}\left(\frac{x}{\Delta}\right)$$

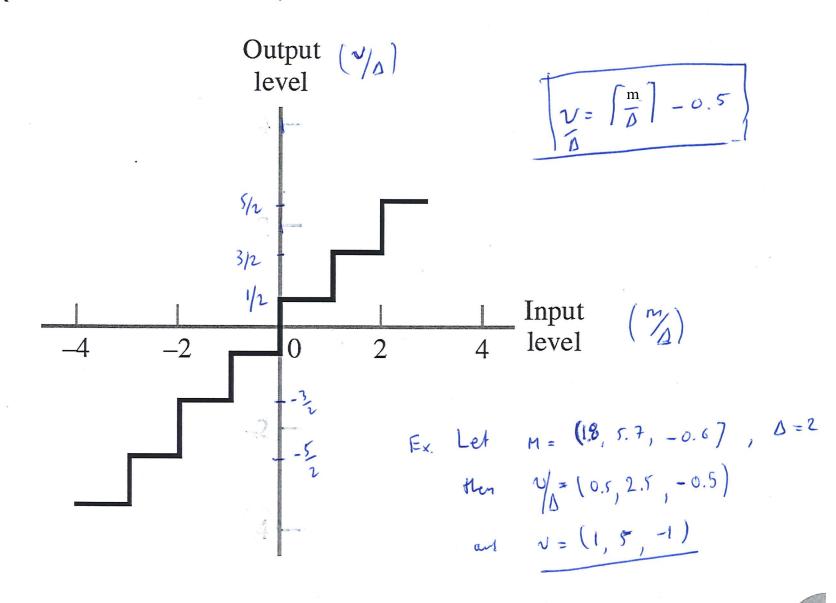
 $\therefore x_q = [1, 3, 0] \Rightarrow \text{dequanitze} \Rightarrow \hat{x} = x_q \cdot \Delta = [2, 6, 0]$

MSE =
$$\frac{1}{N} \sum_{n=0}^{N-1} (\hat{x}_n - x_n)^2$$

= $\frac{1}{3} (0.2^2 + 0.3^2 + 0.6^2)$
= $0.49/3 \approx 0.163$

Uniform Quantization

Midrise Quantizer: A is the step size



Ex. 2: Apply uniform midrise quantizer: $x_q = \left\lceil \frac{x}{\Delta} \right\rceil - 0.5$ $\therefore x_q = [0.5, 2.5, -0.5]$ $\hat{x} = x_q \cdot \Delta = [1, 5, -1]$ MSE $= \frac{1}{3}(0.8^2 + 0.7^2 + 0.4^2)$

 $= 0.129/3 \approx 0.43$

Ex. 3: Assume x is uniformly distributed in the range [-8, 8]. Which quantizer should we use if N is even?

 \Rightarrow Uniform midrise quantizer, because it allows symmetric matching of positive and negative range with an even number of quantization bins (since zero is *not* a reconstruction value).

If $\Delta = 2$, what is quantization output rate?

$$N = \frac{x_{\text{max}} - x_{\text{min}}}{\Delta} = 8$$
$$R = \log_2 N = 3 \text{ bits}$$

Ex. 4: What is expected distortion (MSE) for Ex. 3?

$$D = E[(x - \hat{x})^2] = \sum_{i=0}^{N-1} \int_{b_i}^{b_{i+1}} (x - \hat{x}_i)^2 f_X(x) dx$$

 \Rightarrow uniform quantizer and uniform input:

$$\Rightarrow f_X(x) = \frac{1}{16}, -8 \le x \le 8$$
 (remember, for any pdf $\int_{-\infty}^{\infty} f_X(x) = 1$)

Since $\Delta = 2$, the difference between the variable value and the quantizer output reconstruction value, $(x - \hat{x}_i)$, linearly varies between -1 and 1, for each i. Hence, we perform a change of variables that is independent of i.

$$\tilde{x} = x - \hat{x} \implies -1 \le \tilde{x} \le 1$$

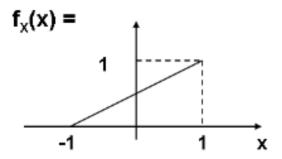
$$\therefore D = \frac{1}{16} \sum_{i=0}^{N-1} \int_{-1}^{1} \tilde{x}^{2} dx$$

$$= \frac{1}{16} \sum_{i=0}^{N-1} \frac{\tilde{x}^{3}}{3} \Big|_{-1}^{1}$$

$$= \frac{1}{16} \sum_{i=0}^{N-1} \frac{2}{3} \rightarrow N = 8$$

$$= \frac{8}{16} \cdot \frac{2}{3} = \frac{1}{3} \quad \left(= \frac{\Delta^{2}}{12} \right)$$

Ex. 5: You have a random variable with the pdf $f_X(x)$ shown below. Calculate the resulting distortion for a 1-bit uniform quantizer with the following parameters: $\Delta = 1$, $x_{\text{max}} = 1$, $x_{\text{min}} = -1$, N = 2, b = [-1, 0, 1], $\hat{x} = [-\frac{1}{2}, \frac{1}{2}]$



$$D = \sum_{i=0}^{N-1} \int_{b_i}^{b_{i+1}} (x - \hat{x}_i)^2 f_X(x) dx$$

$$f_X(x) = \frac{x+1}{2} \Rightarrow = \int_{-1}^0 \left(x - \left(-\frac{1}{2} \right) \right)^2 \left(\frac{x+1}{2} \right) dx + \int_0^1 \left(x - \frac{1}{2} \right)^2 \left(\frac{x+1}{2} \right) dx$$

$$= \int_{-1}^0 \left(x^2 + x + \frac{1}{4} \right) \left(\frac{x+1}{2} \right) dx + \int_0^1 \left(x^2 - x + \frac{1}{4} \right) \left(\frac{x+1}{2} \right) dx$$

$$= \int_{-1}^0 \frac{x^3 + 2x^2 + \frac{5}{4}x + \frac{1}{4}}{2} dx + \int_0^1 \frac{x^3 - \frac{3}{4}x + \frac{1}{4}}{2} dx$$

$$= \frac{1}{2} \left[\left(\frac{x^4}{4} + \frac{2}{3}x^3 + \frac{5}{8}x^2 + \frac{1}{4}x \right) \Big|_{-1}^0 + \left(\frac{x^4}{4} - \frac{3}{8}x^2 + \frac{1}{4}x \right) \Big|_0^1 \right]$$

$$= \frac{1}{2} \left(\frac{4}{24} \right) = \frac{1}{12}$$

Ex. 6: Calculate SQNR (Signal to Quantization Noise Ratio) for Ex. 5.

$$SQNR = 10 \log_{10} \frac{\sigma_X^2}{\sigma_e^2} \implies \sigma_e^2 = \frac{1}{12}$$

$$\mu_X = \int_{-\infty}^{\infty} x f_X(x) dx$$

$$= \int_{-1}^{1} \frac{x(x+1)}{2} dx$$

$$= \frac{1}{2} \left(\frac{x^3}{3} + \frac{x^2}{2} \right) \Big|_{-1}^{1}$$

$$= \frac{1}{2} \left(\frac{2}{3} \right) = \frac{1}{3}$$

$$\sigma_X^2 = \int_{-\infty}^{\infty} (x - \mu_X)^2 f_X(x) dx
= \int_{-\infty}^{\infty} x^2 f_X(x) dx - \mu_X^2 \quad \text{(this is a standard identity - try to derive it yourself)}
= \int_{-1}^{1} x^2 \left(\frac{x+1}{2}\right) dx - \left(\frac{1}{3}\right)^2
= \frac{1}{2} \left[\frac{x^4}{4} + \frac{x^3}{3}\right]_{-1}^{1} - \frac{1}{9}
= \frac{1}{3} - \frac{1}{9} = \frac{2}{9}$$

$$\therefore \text{ SQNR} = 10 \log_{10} \left(\frac{2}{9} \cdot \frac{12}{1} \right)$$
$$= 10 \log_{10} \left(\frac{8}{3} \right) = 4.26 \text{ dB}$$

Ex. 7: Use the Max-Lloyd algorithm to design a non-uniform quantizer for Ex. 5. Initialize that algorithm using the uniform quantizer previously defined: b = [-1, 0, 1]; reconstruction values $\hat{x} = [-\frac{1}{2}, \frac{1}{2}]$. Note: the first and last values in b (b_0 and b_2 in this case) are technically not decision boundaries, but the quantizer end points, x_{\min} and x_{\max} respectively. An N-level quantizer, has N-1 decision boundaries and N reconstruction values.

1st Iteration:

$$b_i = \frac{\hat{x}_{i-1} + \hat{x}_i}{2}$$
, $\therefore b_1 = 0$ (\checkmark already the case)
$$\hat{x}_i = \frac{\int_{b_i}^{b_{i+1}} x f_X(x) dx}{\int_{b_i}^{b_{i+1}} f_X(x) dx}$$

$$\therefore \hat{x}_{0} = \frac{\int_{-1}^{0} \frac{x(x+1)}{2} dx}{\int_{-1}^{0} \frac{(x+1)}{2} dx} = \frac{\left(\frac{x^{3}}{3} + \frac{x^{2}}{2}\right)\Big|_{-1}^{0}}{\left(\frac{x^{2}}{2} + x\right)\Big|_{-1}^{0}} = -\frac{1}{3}$$

$$\hat{x}_{1} = \frac{\int_{0}^{1} \frac{x(x+1)}{2} dx}{\int_{0}^{1} \frac{(x+1)}{2} dx} = \frac{\left(\frac{x^{3}}{3} + \frac{x^{2}}{2}\right)\Big|_{0}^{1}}{\left(\frac{x^{2}}{2} + x\right)\Big|_{0}^{1}} = \frac{5}{9}$$

$$\therefore \hat{x} = \left[-\frac{1}{3}, \frac{5}{9}\right]$$

Ex. 8: Ex. 8.5, p.221 in text Note: there is an inconsistency in text: they describe the use of the autocorrelation matrix R_X for deriving the KLT, but then use the autocovariance matrix C_X in the example. The KLT does in fact use C_X (though, some people define R_X as we define C_X !), but we often have/assume zero-mean processes ($\mu_X = 0$), therefore $R_X = C_X$.

Ex. $8.5 \Rightarrow \text{Let us assume } X \text{ is a zero-mean process}$

We have N=4 sample sequences of length 3 $(X(i), i=\{0,1,2\})$:

$$x_0 = [4, 4, 5], x_1 = [3, 2, 5], x_2 = [5, 7, 6], x_4 = [6, 7, 7]$$

$$R_X = E[XX^T] = E\left(\begin{bmatrix} X(0) \\ X(1) \\ X(2) \end{bmatrix} [X(0)X(1)X(2)]\right)$$

$$= \begin{bmatrix} E[X(0)X(0)] & E[X(1)X(0)] & E[X(2)X(0)] \\ E[X(0)X(1)] & E[X(1)X(1)] & E[X(2)X(1)] \\ E[X(0)X(2)] & E[X(1)X(2)] & E[X(2)X(2)] \end{bmatrix}$$

Note: diagonal of R_X , $R_X(i,i) = E[X(i)^2] = \sigma_{X(i)}^2$ (when $\mu_X = 0$)

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$$\Rightarrow \text{ Estimate } R_X(i,j) = \frac{1}{N-1} \sum_{n=0}^{N-1} x_n(i) x_n(j)$$

$$= \begin{bmatrix} 28.67 & 33 & 35.67 \\ 33 & 39.33 & 40.33 \\ 35.67 & 40.33 & 45 \end{bmatrix}$$

Find the eigenvalues of R_X :

$$\Rightarrow |\lambda I - R_X| = 0 \Rightarrow \lambda = \{111.2052, 1.7485, 0.0463\}$$

where $|\cdot|$ is the determinant operator.

And the eigenvectors:

$$R_X u = \lambda u \Rightarrow u_o = [0.5073, 0.5870, 0.6301]$$

 $u_1 = [0.0794, -0.7609, 0.6440]$
 $u_2 = [-0.8581, 0.2766, 0.4326]$

These eigenvectors from R_X are the bases of the KLT, and thus are assembled as the rows of the transform matrix F:

$$y = Fx \implies F = \begin{bmatrix} u_0 \\ u_1 \\ u_2 \end{bmatrix}$$

Remember:

$$R_Y = E[YY^T]$$

$$= E[FXX^TF^T]$$

$$= FE[XX^T]F^T$$

$$= FR_XF^T$$

For KLT:

$$R_Y = \begin{bmatrix} \lambda & 0 \\ & \ddots & \\ 0 & \lambda_{N-1} \end{bmatrix}$$

$$\therefore \lambda_i = \sigma_{Y(i)}^2 \text{ (for } \mu_Y = 0)$$

Note: λ_0 is large compared to others \Rightarrow good energy compaction.

We can easily calculate

$$G_{TC_Y} = \frac{\frac{1}{N} \sum_{i=0}^{N-1} \sigma_{Y(i)}^2}{\left(\prod_{i=0}^{N-1} \sigma_{Y(i)}^2\right)^{1/N}} = 18.1082$$

$$\Rightarrow G_{TC_Y} = 1.0174$$

Note: $G_{TC_X} = 1$ if $\sigma_{X(i)}^2 = \sigma_X^2$ for all i

Also note that the transform is energy preserving $\sum \sigma_X^2 = \sum \sigma_Y^2$ (since it is orthonormal).

Ex. 9: X is a zero-mean process with $R_X(i,j) = 0.95^{|i-j|}$

$$R_X = \begin{bmatrix} 1 & 0.95 & 0.9025 & 0.8574 \\ 0.95 & 1 & 0.95 & 0.9025 \\ 0.9025 & 0.95 & 1 & 0.95 \\ 0.8574 & 0.9025 & 0.95 & 1 \end{bmatrix}$$

$$\Rightarrow k = |i - j|; \Rightarrow R_X(k) = 0.95^k = E[X(i)X(i \pm k)]$$

The process is (wide-sense) stationary – the autocorrelation only depends on the distance between the two "points" (k), not the absolute position (i).

Given transform

$$F = \begin{bmatrix} 0.25 & 0.25 & 0.25 & 0.25 \\ 0.4 & 0.2 & -0.2 & -0.4 \\ 0.25 & -0.25 & -0.25 & 0.25 \\ 0.2 & -0.4 & 0.4 & -0.2 \end{bmatrix}$$
(DCT Approximation)

Note F is not orthonormal.

Find $\sigma_{Y(i)}^2$ for y = Fx:

 $R_Y = FR_XF^T \rightarrow \text{but}$, we only need diagonals – no need to perform entire matrix multiplication

Note F is not orthonormal.

Find $\sigma_{Y(i)}^2$ for y = Fx:

$$\begin{array}{lll} R_Y & = & FR_XF^T \to \text{ but, we only need diagonals - no need to perform entire matrix multiplication} \\ \therefore \sigma_{Y(0)}^2 & = & E[Y_0^2] \\ & = & E\left[\left(0.25 \cdot X(0) + 0.25 \cdot X(1) + 0.25 \cdot X(2) + 0.25 \cdot X(3)\right)^2\right] \\ & = & \frac{1}{4}\left[E[X(0)^2] + E[X(0)X(1)] + \ldots\right] \\ \sigma_{Y(1)}^2 & = & E[Y(1)^2] \\ & = & E\left[\left(0.4 \cdot X(0) + 0.2 \cdot X(1) - 0.2 \cdot X(2) - 0.4 \cdot X(3)\right)^2\right] \\ & \dots \\ \therefore \sigma_{Y(i)}^2 & = & [0.939, 0.0648, 0.0128, 0.0122] \end{array}$$